

# Continuous Time Equations for Analog Tape Modeling

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## Record head

For an instantaneous current  $I$ , the magnetic field output of the record head is given as a function of distance along the tape 'x', and depth into the tape 'y' (Karlqvist medium field approximation) [Bertram, page 60]:

$$H_x(x, y) = \frac{1}{\pi} H_0 \left( \tan^{-1} \left( \frac{(g/2) + x}{y} \right) + \tan^{-1} \left( \frac{(g/2) - x}{y} \right) \right)$$
$$H_y(x, y) = \frac{1}{2\pi} H_0 \ln \left( \frac{((g/2) - x)^2 + y^2}{((g/2) + x)^2 + y^2} \right)$$

where  $g$  = head gap, and  $H_0$  = deep gap field, given by:

$$H_0 = \frac{NIE}{g}$$

where  $N$  = number of turns coils of wire around the head, and  $E$  = head efficiency given by:

$$E = \frac{1}{1 + \frac{l A_g}{\mu_r g} \int_{core} \frac{d\vec{l}}{A(l)}}$$

where  $A_g$  is the gap area,  $\mu_r$  is the core permeability relative to free space ( $\mu_0$ ),  $g$  is the gap width, and  $A(l)$  is the cross-sectional area of the core as a function of length.

## Tape Magnetisation

### Deadzone

For low current, the field is insufficient to create a change in magnetisation. For high current the field saturates. The effective field magnetising the tape  $H_h$  can be described as follows:

$$H_h = \begin{cases} 0 & H \leq S^* H_c \\ H & H > S^* H_c \end{cases}$$

where  $S^*$  = hysteresis loop squareness, and  $H_c$  = coercivity.

### Hysteresis

The magnetostatic field recorded to magnetic tape can be described using a hysteresis loop. A circuit simulation of a hysteresis loop by Martin Holters and Udo Zolzer, using the Jiles-Atherton magnetisation model can be found at [http://dafx16.vutbr.cz/dafxpapers/08-DAFx-16\\_paper\\_10-PN.pdf](http://dafx16.vutbr.cz/dafxpapers/08-DAFx-16_paper_10-PN.pdf). They use the following differential equation to describe magnetisation 'M' as a function of magnetic field 'H':

$$\frac{dM}{dH} = \frac{(1-c)\delta_M(M_{an}-M)}{(1-c)\delta k - \alpha(M_{an}-M)} + c \frac{dM_{an}}{dH}$$

where  $M_{an}$  is the anisotropic magnetisation given by:

$$M_{an} = M_s L\left(\frac{H + \alpha M}{a}\right)$$

where  $M_s$  is the magnetisation saturation, and  $L$  is the Langevin function.

## Playback head

### Ideal playback voltage

The ideal playback voltage as a function of tape magnetisation is given by [Bertram, page 121]:

$$V(x) = NW E v \mu_0 \int_{-\infty}^{\infty} dx' \int_{-\delta/2}^{\delta/2} dy' \vec{h}(x' + x, y') \cdot \frac{\vec{M}(x', y')}{dx}$$

where  $N$  = number of turns of wire,  $W$  = width of the playhead,  $E$  = playhead efficiency,  $v$  = tape speed. Note that  $V(x) = V(vt)$  for constant  $v$ .  $\vec{h}(x, y)$  is defined as:

$$\vec{h}(x, y) \equiv \frac{\vec{H}(x, y)}{NIE}$$

where  $\vec{H}(x, y)$  is the same as for the record head.

### Loss effects

There are several frequency-dependent loss effects associated with playback, described as follows [Kadis, page 126]:

$$V(x) = V_0(x)[e^{-kd}] \left[ \frac{1 - e^{-k\delta}}{k\delta} \right] \left[ \frac{\sin(kg/2)}{kg/2} \right]$$

where  $k$  = wave number.

### Spacing Loss

$$g_s = e^{-kd}$$

where  $d$  is the distance between the tape and the playhead.

### Gap Loss

$$g_g = \frac{\sin(kg/2)}{kg/2}$$

where  $g$  is the gap with of the play head.

### Thickness Loss

$$g_t = \frac{1 - e^{-k\delta}}{k\delta}$$

where  $\delta$  is the thickness of the tape.

## Conclusion

If each of these components is digitized, a digital physical model of the analog tape machine can be constructed.